

ActionBot: Action Type – Web Integration

Brief Overview

Enable an ActionBot conversation's ending-action to connect to a separate Editor System. This allows you to collect conversation parameters and then run automated Smart Walk-Thrus on a Web application.

How It Works

- First, create an Automated Smart Walk-Thru
- Automated Steps set to "Fill" require a dynamic conversation parameter in this format:
 - \$(parameter_name)
 - Example: \$(amount)
- Copy and document each Automated Fill Step's dynamic conversation parameters, you'll need it later.
- Once the ASWT is complete, copy and document its permalink, you'll need it later.
- Next, change the Storage Manager settings to:
 - Cross Domain – Proxy > Standard



- Publish your Automated Smart Walk-Thru to the same environment as the Workstation

ActionBot Configuration:

- Switch the account from the Web Editor to the Editor System with the ActionBot via the System Switcher
- Within the Editor, change the Item's dropdown to ActionBot
- Within the ActionBots App, add a new Bot
 - **Note:** Workstation may ONLY contain one ActionBot with multiple Conversations
- Next, Create a Conversation
- Add Conversation Questions as needed
- End the Conversation with an Added Action



- Name the Action

- Next, set the Added Action Type to “Web Integration”




- Next, from the Web System dropdown, select the Editor Web System from the desired Account to Integrate with



- Now, input the Destination URL for the Action’s redirect (For dynamic URL BB code supported)
- Then, input the Smart Walk Thru’s Permalink from the selected Editor Web System



- Under the “Data the Web Integration Requires” section:
 1. From the dropdown, reference the Conversation Question
 2. Within the input labeled “Name as,” add the matching dynamic conversation parameters applied to the corresponding Automated Fill Step
 3. Now, click **Save Action to Conversation**
 4. Publish the Bot and Conversation to the same environment as the Web SWT
 5. **Configuration complete**